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25. The computer-implemented system of claim 24, wherein the hub computing device is further configured to receive signals from sensors in the structure, identify at least one substructure of the structure based on at least one pattern of motion determined based on the signals from the sensors, and update a map of the structure based on the at least one identified substructure and the location of one or of the sensors whose signals were used to determine the at least one pattern of motion.

26. The computer-implemented system of claim 24, wherein the hub computing device is further configured to receive signals from sensors in the structure, receive context data comprising at least the time of day, identify at least one pattern of motion based on the context data and directional motion determined from the signals from the sensors, and update a model of motion patterns with the at least one identified pattern of motion.

27. The computer-implemented system of claim of claim 26, wherein the hub computing device is further configured to receive additional signals from the sensors in the structure, receive additional context data comprising at least the time of day, and determine if the additional context data and directional motion determined from the additional signals corresponds to at least one pattern of motion in the model of motion patterns or diverges from the patterns of motion in the model of motion patterns.

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28. The computer-implemented system of claim 27, wherein the hub computing device is further configured to, when the additional context data and the directional motion determined from the additional signals corresponds to at least one pattern of motion in the model of motion patterns, in response to determining that the additional context data and the directional motion determined from the additional signals corresponds to at least one pattern of motion in the model of motion patterns, generate a second control signal for the device in the structure and send the second control signal to the device in the structure to be implemented by the device.

29. The computer-implemented system of claim 27, wherein the hub computing device is further configured to, when the additional context data and the directional motion determined from the additional signals diverges from the patterns of motion in the model of motion patterns, in response to determining that the additional context data and the directional motion determined from the additional signals diverges from the patterns of motion in the model of motion patterns, generate an alert indication and send the alert indication to at least one communications device.

30. The computer-implemented system of claim 29, wherein the alert indication comprises an indication of unexpected motion or an indication of lack of expected motion.

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